# Modul ASM 3901 – Mathematical Methods in Engineering

1	Module Number 3901	Study Programme ASM	Semester 1	Offered in XWS □SS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Points 7
2	2 Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
	a) Numerical Ana b) Numerical Diff	lysis erential Equations	Lecture Lecture		<b>(SWS)</b> 4 3	<b>(h)</b> 60 45	<b>(h)</b> 105	Englisch
3	Learning Outcomes Once the module has Knowledge and Unit explain underst underst Use, Application and Use and Transfer apply th analyse recogni analyse familian Scientific Innovat use me create f optimiz indepen develop Communication un interpro use the aspects. commu Scientific Self-Conco justify t	a and Competences as been successfull derstanding the basic ideas of tand the algorithm tand the limitation: ad Generation of Ki the algorithms in M. the solutions cond ze and classify con the solutions cond the solution theore and cooperation the results of nu learned knowledg unicate and coopera- the solution theore	y completed, the numerical analysis and their consists of the algorithe nowledge ATLAB. Exerning plausibinections. Is and derive or henew ideas an gain new insight proaches for ne optimization of merical analysis e, skills and cor ate within the ge alism tically and met	ne students can. ysis and underst straints ims lity develop solutic d topics based o nts in the field of ew concepts and technical applic s and draw adm npetences to ev group in order to hodically.	and the relation ons. on their basic kr f numerical anal d assess their su ations. issible conclusio aluate the field o find adequate	n to the applicat nowledge. lysis. nitability. and interpret th solutions for the	ions nem according to e task at hand.	o other
<ul> <li>4 Contents         <ul> <li>Lecture a)</li> <li>Linear systems</li> <li>Regression</li> <li>Numerical differentiation and integration</li> <li>Nonliniear equations and nonlinear systems</li> <li>Interpolation</li> <li>Lecture b)</li> <li>Ordinary differential equations (Runge-Kutta methods, multistep methods, stability and stiffness, sh methods)</li> <li>Partial differential equations (finite difference methods, finite element methods)</li> <li>Programming in Matlab as part of the lecture.</li> </ul> </li> <li>5 Participation Requirements</li> </ul>					nd stiffness, sho	oting		
	compulsory: - recommended: Good knowledge of higher mathematics							

# Modul ASM 3901 – Mathematical Methods in Engineering

6	Examination Forms and Prerequisites for Awarding ECTS Points						
	Written Examination, 120 minutes						
7	Further Use of Module Applying mathematical methods in other lectures and major fields of automotive engineering						
8	Module Manager and Full-Time Lecturer Prof. Dr. J. Gaukel, Prof. Dr. M. Stämpfle						
9	<ul> <li>Literature</li> <li>Gander W., Gander M.J., Kwok, F., Scientific Computing</li> <li>Stanoyevitch, Introduction to Numerical Ordinary and Partial Differential Equations Using MATLAB, Wiley</li> <li>Hairer, Norsett, Wanner: Solving Ordinary Differential Equations I, II, Springer</li> <li>Smith: Numerical Solution of Partial Differential Equations: Finite Difference Methods, Oxford University Press</li> </ul>						
10	Last Updated 18.03.2019						

### Modul ASM 3902 – System Design

22 Cc a) b) 33 Le O Kı	Automotive Sys Software Archir Automotive Sys Development P System Test earning Outcomes nce the module ha analyze develop develop evork in developm	stem and tectures stems Process and and Competences as been successfull automotive E/E (e o own solutions in t a larger interdisci ent processes nece derstanding	Teaching and Forms Lecture Lecture y completed, the lectronic/electronic his application plinary enginee essary.	Learning ne students can ric) architecture domain ering team base	Cont: (SWS) 4 4 s and the associ	act Time (h) 60 60	Self-Study Time (h) 120	<b>Language</b> English					
a) b) 3 Le O Kı	Automotive Sys Software Archi Automotive Sys Development F System Test earning Outcomes nce the module ha analyze develop work in developm	stem and tectures stems Process and and Competences as been successfull automotive E/E (e o own solutions in t a larger interdisci ent processes nece derstanding	Lecture Lecture y completed, th lectronic/electr his application plinary enginee essary.	ne students can ric) architecture domain ering team base	(SWS) 4 4  s and the associ	(h) 60 60	<b>(h)</b> 120	English					
a) b) 3 Le O Kı	Automotive Sys Software Archi Automotive Sys Development P System Test earning Outcomes nce the module ha analyze develop work in developm	stem and tectures stems Process and and Competences as been successfull automotive E/E (e o own solutions in t a larger interdisci ent processes nece derstanding	Lecture Lecture y completed, th lectronic/electr his application plinary enginee essary.	ne students can ric) architecture domain ring team base	4 4  s and the associ	60 60	120	English					
b) 3 Le O Kı	Automotive Sys Development F System Test earning Outcomes nce the module ha analyze develop work in developm	and Competences and Competences as been successfull automotive E/E (e o own solutions in t a larger interdisci ent processes nece derstanding	Lecture y completed, th lectronic/electr his application plinary enginee essary.	ne students can ric) architecture domain ring team base	4  s and the associ	60							
3 Le O Kı	earning Outcomes nce the module ha analyze develop work in developm	and Competences as been successfull automotive E/E (e o own solutions in t a larger interdisci ent processes nece derstanding	y completed, th lectronic/electr his application plinary enginee essary.	ne students can ric) architecture domain ering team base	 s and the associ	I							
Kı	nowledge and Und	derstanding			<ul> <li>3 Learning Outcomes and Competences         Once the module has been successfully completed, the students can         <ul> <li> analyze automotive E/E (electronic/electric) architectures and the associated hardware and software architectu</li> <li> develop own solutions in this application domain</li> <li> work in a larger interdisciplinary engineering team based on a clear understanding of the required design and development processes necessary.</li> </ul> </li> </ul>								
	<ul> <li> underst</li> <li> know th problems</li> </ul>	and the architectu ne limits of existing to be solved in the	re of automotiv systems, have future.	ve electric and o an idea about f	electronic syster uture trends in t	ns and their dev the automotive	elopment proce E/E domain and	ess. about the					
U	se, Application an	d Generation of K	nowledge										
	<ul> <li>Use and Transfer</li> <li>understand the complete automotive system development process including system test and application.</li> <li>see the difference between systems, functions and components and their respective development processes.</li> <li> analyse the structure of distributed automotive electronic systems, their software architectures and the communication principles and channels.</li> <li> be able to analyze communication protocols, especially bandwidth and latency.</li> <li> be able to assess the safety and reliability of systems.</li> <li>compare automotive solutions with solutions and concepts from other technical domains.</li> </ul>							n. Isses.					
	Scientific Innovati	ion											
	use met	thods and tools to	gain new insigh	its.									
	create r	nodels for automo	tive systems an	id use them for ith respect to fu	implementation	n and tests.	ca robustness a	nd cost					
	<ul> <li> optimiz</li> <li> set up a</li> </ul>	and evaluate hypot	hesis tests and	design procedu	ires to verify and	d validate the E/	E design.	nu cost.					
	indeper     concepts a	ndently develop ap and solutions from	proaches for ne other technica	ew systems and I fields, e.g. aer	assess their sui ospace or comp	tability, especia uter science into	lly transfer related the automotive	ed technical e domain.					
C	<ul> <li>Communication and Cooperation <ul> <li> communicate actively within an organization and obtain information.</li> <li> interpret the results of the field and draw admissible conclusions.</li> <li> use the learned knowledge, skills and competences to evaluate E/E concepts and assess their features.</li> <li> present automotive system design related topics and discuss them.</li> <li> communicate and cooperate within an engineering team in order to find adequate solutions for the task at hand.</li> </ul> </li> </ul>												
Sc	cientific Self-Conce	eption/ Profession	alism										
	<ul> <li> analyze recomment</li> <li> justify t</li> </ul>	the impact of desi ndations for decision he solution theore	gn decisions on ons from a socia tically and metl	the social and al and ethical p hodically.	economic situat erspective on th	ion of the socie e basis of the ar	ty and derive alyses and evalu	uations made.					
				Broup compan	son and develop	strategies to In	ipiove them.						

### Modul ASM 3902 – System Design

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4	Contents Lecture a): System Development					
	<ul> <li>Typical components and functions of automotive systems.</li> </ul>					
	<ul> <li>Typical engine management system and its development process.</li> </ul>					
	<ul> <li>Software life cycle including classic V model, agile (Scrum) development and Automotive Spice.</li> </ul>					
	Requirements engineering and requirements management.					
	<ul> <li>SW-documentation and data specification, coding guidelines.</li> </ul>					
	Software and system test.					
	Application examples of simple functions					
	Lecture b):					
	Application domains powertrain, chassis, body, advanced driver assistance, infotainment, outlook to automated driving					
	<ul> <li>Basics of distributed systems. ECU hardware requirements and structure, communication relations and communication problems under real-time constraints.</li> </ul>					
	• E/E architecture of hybrid and electric powered cars vs. cars with classic combustion engines. Trend towards domain controller and compute-server-architectures.					
	<ul> <li>Automotive bus systems and communication protocols (CAN, LIN, FlexRay, MOST, Automotive Ethernet, V2X). Message based communication vs. service oriented communication.</li> </ul>					
	Diagnosis and diagnostic communication.					
	Qualitative and quantitative assessment of system safety and reliability. Functional safety including ISO 26262.					
	ECU software architecture and software standards (AUTOSAR Classic and Adaptive)					
	The lectures will include theory, case studies, literature surveys and presentation of selected topics done by student teams.					
5	Participation Requirements					
	compulsory					
	Basic knowledge in electronics and computer science.					
	Familiarity with one of the major programming languages, C/C++ preferred.					
	Own experience in sen-management of a project, i.e. Bachelor thesis					
6	Examination Forms and Prerequisites for Awarding ECTS Points					
	Written Examination 120 min					
7	Further Use of Module					
	3909 Reliable Embedded Systems 3911 Powertrain 3912 Electric and Electronic Architecture					
8	Module Manager and Full-Time Lecturer					
	Prof. Dr. W. Zimmermann					
9	Literature					
	a - L Schöuffele, T. Zurouker Automotive Software Fraincasian Crainasa Viewar					
	J. Schaumere, T. Zurawka: Automotive Software Engineering. Springer-Vieweg.					
	K.K. Jurgen. Automotive Electronics Handbook. McGraw-Hill.					
	w. Zimmermann, R. Schmidgall: Bussysteme in der Fahrzeugtechnik, Springer-Vieweg.					
	• K. Keir (Publisher): Bosch Automotive Handbook Series. Springer-Vieweg.					
10	Last Updated					
	02.05.2019					

1	Module Number 3903	Study Programme ASM	Semester 1	Offered in XWS □SS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Points 8		
2	2 Courses		Teaching and Forms	Learning	Contact Time		Self-Study Time	Language		
					(SWS)	(h)	(h)			
	a) Basic Control		Lecture		3	45	120	Englisch		
	b) Advanced Con	trol	Lecture		3	45				
	c) Lab Simulation	and Control 1	Lab		2	30				
3 Learning Outcomes and Competences Once the module has been successfully completed, the students can										
	<ul> <li>Knowledge and Understanding</li> <li> understand and know the basic methods of system simulation and control engineering</li> <li> know how and where to use these methods in the development of automotive systems</li> </ul>									
	Use, Application an	Use, Application and Generation of Knowledge								
	Use and Transfer									
	<ul> <li> apply p</li> <li> apply n</li> <li> analyse</li> </ul>	nethods of system and evaluate the l	simulation and behaviour of au	control enginee	ring in automotive ms by use of sim	ive applications ive applications aulation results				
	Scientific Innovat	ion								
	<ul> <li> use simulation and control engineering methods and tools to gain new insights into automotive system.</li> <li> create and optimize the behaviour of automotive systems based on system models</li> </ul>									
	<ul> <li>Communication und Cooperation         <ul> <li> create, communicate and discuss technical information's in the area of the course subject</li> <li> communicate actively within an organization and obtain information.</li> </ul> </li> <li>Scientific Self-Conception/ Professionalism         <ul> <li> justify the solution theoretically and methodically to improve development methods.</li> </ul> </li> </ul>									
4	• reflect	and assess one s ov	wh addittes in a	group comparis	son.					
4	1. Basic Contro	bl								
	Systemati	ic System Modellin	g and Identifica	tion						
	System Re     Simulation	epresentation of SI	SO Systems (e.§	g. LDE, Transfer	functions, Block	diagrams)				
	<ul> <li>Simulation</li> <li>Stability C</li> <li>Continuor</li> </ul>	Criteria and Freque	ncy Response -Controller Des	sign						
	<b>3</b> Adversed <b>6</b>	outual								
	<ul> <li>Advanced C</li> <li>Linear and</li> </ul>	d non-linear State S	Space Represen	tation						
	State Space	ce Controller Desig	n							
	Observer     Digital Co	Design and Separa	tion Theorem	n						
	LQR-Cont	roller Design	te space Desigi	1						
	3. Advanced C	ontrol II								
	<ul> <li>System Modelling using State Machines (FSM)</li> <li>Control Design with Fuzzy Control (FUZ)</li> </ul>									
	4. Computer L	ab								
	System Re	epresentations usir	ng Matlab/Simu	llink, Numerical	Simulation					
	<ul> <li>iviodelling</li> <li>Controller</li> </ul>	r Design of an Elect	ric Drive Syster	ngn of an Electri n	c Drive System					
	<ul> <li>System M</li> <li>MATLAB /</li> </ul>	lodelling and Simul / SIMULINK / STATE	ation of State N FLOW Refresh	Machines and Fu er Course	izzy Control app	lications				

5	Participation Requirements						
	compulsory: Mathematics, Physics, Mechanics						
	recommended: Control Engineering Basics, Basics in Matlab/Simulink						
6	Examination Forms and Prerequisites for Awarding ECTS Points						
0	Written Examination, 120 minutes						
7	Further Use of Module						
	Simulation and Control 2						
8	Module Manager and Full-Time Lecturer						
	Prof. DrIng. Gerd Wittler, Prof. DrIng. Walter Lindermeir						
9	Literature						
	Lecture Notes and Scripts						
	Ogata, K.: Modern Control Engineering, Pearson Verlag						
	Liu, Xiangjie: Systems Control Theory, Science Press Beijing						
	Palm, W. J.: MATLAB for Engineering Applications, McGraw-Hill						
	Hanselman D.C., Littlefield B.: Mastering Matlab, Pearson Verlag						
	Dabney, J.B.; Harman, T.L.: Mastering Simulink						
	Mohthari: Engineering Applications in Process Control, Fuzzy Control						
10	Last Updated						
	16.4.2019						

### Modul ASM 3904 – Vehicle Technology

1	<b>Module Number</b> 3904	Study Programme ASM	Semester 1	Offered in XWS □SS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Points 7		
2	Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language		
					(SWS)	(h)	(h)			
	a) Motor Vehicles	5	Lecture		3	45	105	Englisch		
	b) Internal Comb	ustion Engines	Lecture		3	45				
	c) Lab Motor Veh	icles	Lab		1	15				
3	Learning Outcomes and Competences Once the module has been successfully completed, the students can Knowledge and Understanding									
	<ul> <li> explain the basic terms in vehicle technology and internal combustion engine technology</li> <li> describe the different vehicle concepts like front wheel, rear wheel and 4-wheel-drive</li> <li> explain basic component parts of the chassis and the drive train</li> <li> understand and calculate Rolling resistance, aerodynamic drag, climbing and acceleration resistance</li> <li> recognize the significance of the reduction of driving resistance for lowering fuel consumption and emissions</li> <li> understand the relationship between power curve of combustion engines and the force and wheel speed at the driven wheels</li> </ul>									
	Use, Application and Generation of Knowledge         Use and Transfer         • choose the best engine and driveline combination for different types of vehicles.         • create testing reports and present test results.         • analyse the state of the art wheel suspension systems         • understand the physical behaviour of forces between road and tyre for vehicle dynamics simulation         • familiarize themselves with new ideas and topics in the field of automotive powertrains and suspensions									
	<ul> <li>Scientific Innovation</li> <li> find new technologies to lower fuel consumption and exhaust emissions of internal combustion engines.</li> <li> optimize powertrains for high driving performance</li> <li> set up new driving test procedures</li> <li> calibrate tyre models to measurements</li> <li> independently develop approaches for new suspension and driveline concepts and assess their suitability</li> </ul>									
	Communication un	d Cooperation								
	<ul> <li> communicate actively within a research or development team and obtain information.</li> <li> interpret the results of vehicle testing and draw admissible conclusions.</li> <li> communicate with engine and chassis designers about new solutions</li> </ul>									
	Scientific Self-Conc	eption/ Profession	alism							
	<ul> <li> derive recommendations for decisions from an environmental and safety perspective on the basis of the analyses and evaluations made.</li> <li> justify the solution theoretically and methodically</li> </ul>									

### Modul ASM 3904 – Vehicle Technology

4	Contents						
	a) Lecture: Motor Vehicles						
	The course gives a basic knowledge in vehicle technology and their components The power train is mainly focused The aim is to learn the ability to calculate driving resistance and to design the power train with respect to driving performance and fuel consumption						
	b) Lecture: Internal Combustion Engines						
	Internal Combustion Engine Fundamentals: Mechanics, Design, Kinematics, Thermodynamics, Gas Exchange, Mixture Preparation, Combustion, Emissions New Technologies, Developments and Trends of the Drive Train Advanced Knowledge in the fields of Engine Management, Turbo Charging and Direct Injection						
	c) Lab: Motor Vehicles						
	Determination of full-load torque and power pattern by using the car test bench Detection of fuel consumption map Determination of a tyre map by using the tyre test bench EUREPA. Analysis of vehicle road tests						
5	Participation Requirements						
	compulsory: no recommended: Fundamentals of Engineering Mechanics						
6	Examination Forms and Prerequisites for Awarding ECTS Points						
	Written Examination 120 Minutes						
7	Further Use of Module						
	3906 Simulation and Control 2 3907 Team Project						
8	Module Manager and Full-Time Lecturer						
	Prof. Dr. K.L. Haken						
9	Literature Heywood, J.B. Internal Combustion Engine Fundamentals McGraw-Hill BOSCH Automotive Handbook Distribution SAE						
10	Last Updated 13.06.2019						

#### Modul ASM 3905 – Electronics, Sensors and Measurement Techniques

1	<b>Module Number</b> 3905	Study Program ASM	Semester 1	Offered in XWS □SS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Points 7
2	Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
					(SWS)	(h)	(h)	
	a) Electronic Syste	ems	Lecture		3	45	105	English
	<ul> <li>b) Sensors and Measurement Technology</li> </ul>		Lecture		3	45		
	c) Lab Actuators		Lab		1	15		
						[1 SWS = 15h]		
3	<ul> <li>3 Learning Outcomes and Competences <ul> <li>Once the module has been successfully completed, the students can</li> </ul> </li> <li>Knowledge and Understanding <ul> <li> understand basic functions of electronic systems.</li> <li> understand analogue and digital acquisition with sensors.</li> <li> evaluate interfaces for sensors.</li> <li> evaluate power stages for inductive loads.</li> <li> recognize the significance of electronics for automotive systems.</li> </ul> </li> </ul>							

#### Use, Application and Generation of Knowledge

#### Use and Transfer

- ... apply technical laws (e.g. Ohm / Kirchhof in OP-amp circuits).
- ... create technical reports and presentations.
- ... analyze technical solutions of EE-architectures for signal acquisition.
- ... recognize and classify connections.
- ... understand the basics of the signal acquisition, amplification and A/D-conversion.
- ... analyze technical problems and derive or develop solutions to integrate sensors in control circuits.
- ... design sensor acquisition concepts.
- ... familiarize themselves with new ideas and topics based on their basic knowledge by doing homework tasks.

#### Scientific Innovation

- ... use methods and tools to gain new insights in the field (by working with Simulation models).
- ... create Simulation models for signal evaluation.
- ... optimize signal detection (e.g. speed detection with an incremental speed sensor).

#### **Communication and Cooperation**

- ... communicate actively within the lectures and obtain information.
- ... interpret the results of the field of sensor signal acquisition and treatment and draw admissible conclusions.
- ... present technical contents and simulation results and discuss them with the class and the lecturer.
- ... communicate and cooperate within the group in order to find adequate solutions for the task at hand.

#### Scientific Self-Conception/ Professionalism

• ... present and justify the solution of homeworks theoretically and methodically.

# Modul ASM 3905 – Electronics, Sensors and Measurement Techniques

4	Contents
	a) Lecture: Electronic Systems
	<ul> <li>terminology in electronic systems,</li> <li>principal mode of operation,</li> <li>block diagram,</li> <li>ECU technology,</li> <li>circuit design of interfaces,</li> <li>bipolar transistors and MOSFET,</li> <li>power stages for automotive applications,</li> <li>hardware and basic programming of microcontrollers</li> </ul>
	<ul> <li>b) Lecture: Sensors and Measurement Technology <ul> <li>(Focus on automotive sensors for analogue and digital signal acquisition and transmission)</li> <li>E/E-Architectures for signal acquisition (Sensor, A/D-conversion / signal conditioning)</li> <li>Signal Theory (Bode-diagram and stability of amplifiers)</li> <li>Resistive, capacitive and inductive based automotive sensors</li> <li>Analogue signal acquisition with Operational Amplifier Circuits, basics, analysis of OA-Circuits , selected examples of basic circuits (inverting / non-inverting amplifier, instrumentation amplifier, integrator, low-pass, adder, comparator and Schmitt Trigger)</li> <li>Digital signal acquisition, theory of digital to analog and analog to digital conversion, DAC principles, ADC circuits (Parallel, Successive Approximation (SAR), Pipelined ADC, Sigma-Delta ADC, voltage and charge integrating circuitries)</li> <li>Examples of Automotive Sensor Circuits (Temperature, pressure, force, angular speed, etc.)</li> <li>Replacing sensors by observers in the control unit (e.g. temperature modeling)</li> </ul> </li> <li>c) Lab: Actuators <ul> <li>Experiment: Investigations about three-phase asynchronous motor on system voltage and with frequency converter.</li> </ul> </li> </ul>
5	Participation Requirements
	Compulsory:     Fundamentals of Mathematics and Physics (electricity teaching)
	Recommended:         part a)       Basics of programming language C         part b)       Basics of programming with Matlab and modeling with Simulink         Fundamentals of electrical engineering including Ohm's law, Kirchhoff's laws, law of induction         Fundamentals of electronic components including capacitors, coils, diodes         part c)       Basics of Electrical Engineering
6	Examination Forms and Prerequisites for Awarding ECTS Points Written Examination 120 Minutes, Lab Report
7	Further Use of Module Simulation an Control 2 Team Project
8	Module Manager and Full-Time Lecturer
	DiplIng. G. Mallebrein

# Modul ASM 3905 – Electronics, Sensors and Measurement Techniques

9	Literature
	Bosch: Automotive Handbook 29 <sup>th</sup> edition or newer - Karl-Heinz Dietsche and Konrad Reif Bosch: "Sensoren im Kraftfahrzeug" - Konrad Reif (only available in German) Tietze Schenk "Halbleiter-Schaltungstechnik" - Tietze, Schenk (only available in German) Infineon: C515C, 8-Bit CMOS Microcontroller Ronald Jurgen: Automotive Electronics Handbook, McGraw Hill For part b) Script from the lecturer: Chapter 06
10	Last Updated 16.06.2019 (by Georg Mallebrein)

1	Mo	odule Number 3906	Study Programme ASM	Semester 2	<b>Offered in</b> WS XSS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Points 7
2	Courses		Teaching and Forms	Learning	Conta	act Time	Self-Study Time	Language	
						(SWS)	(h)	(h)	
	a) Longitudional Dynamics		Lecture		1	15	105	Englisch	
	b) Ride Comfort Modeling and Simulation		Lecture		2	30			
	c) Automotive Controller Systems		Lecture		1	15			
	d)	Lab Long. Dyna Comfort and A Systems	amics,Ride utom. Contr.	Lab		3	45		

Once the	e module has been successfully completed, the students can
Knowler	ge and Understanding
•	understand the modelling of longitudinal lateral und vertical motion of vehicles
•	describe the impact of guspension technology on ride comfort
•	calculate algorithm of the model of linear driver rains
•	calculate eigeninequencies and eigeninoues of infeat drives and their central and understand the connections within the
•	explain the basic types of automotive electric drives and their control and understand the connections within the
	power train domain.
•	describe the working principle of electric drives and the actuation principle with a DC/AC converter.
•	have basic knowledge in thermal modeling of powertrain components and in mechanisms to limit their power in
•	recognize the significance of drive cycle, simulation in entimizing electric neurortrains
•	recognize the significance of drive-cycle simulation in optimizing electric powertrains.
Use, App	plication and Generation of Knowledge
Use a	nd Transfer
•	analyse different suspension technologies.
•	understand the influence of drivetrains on fuel consumption of the engine.
•	use state of the art simulation tools for vehicle dynamics.
•	apply a control strategy for a permanent magnet synchronous machine in a simulation environment.
•	work with Simulink simulation models and interpret simulation results.
•	create energy flow diagrams of drive-cycle simulations of an electric vehicle and recognize the influence of vehicle
	parameters.
•	analyse the problem of component overheating and derive strategies to protect the components.
•	create technical reports and presentations in the domain of electric powertrains.
Scient	ific Innovation
•	use methods and tools to gain new insights in the field of vehicle dynamics.
•	create new models for suspension and drivetrains
•	ontimize conventional and hybrid drivetrains
•	use simulation models and evaluation methods to gain the understanding of hi-directional energy flows in electric
•	vehicles (propulsion / recuperation)
•	ontimize the control strategy for a permanent magnet synchronous machine with the help of the theory of the field
-	oriented control.
•	evaluate simulations and find general rules to minimize the energy consumption of electric vehicle.
Commu	nication und Cooperation
•	communicate actively within a development team with engineers from other disciplines.
•	interpret the results of computer simulations and draw admissible conclusions.
•	present own simulation results to the class and interpret the results.
•	cooperate in small working groups and create a common Laboratory report.
•	use the learned knowledge, skills and competences to evaluate simulation results and interpret them.
Scientifi	c Self-Conception/ Professionalism
•	derive recommendations for decisions from a social and ethical perspective on the basis of the analyses and evaluations made
-	iustify their solutions and results theoretically and methodically in presentations
•	justing their solutions and results theoretically and methodically in presentations.

4	Cor	ntents
	,	
	a)	Lecture: Longitudional Dynamics
		simulation models for powertrains in Simulink
		transient behaviour of flexible drive-trains
		fuel- and energy consumption of hybrid and electrical cars
	b)	Lecture: Ride Comfort Modeling and Simulation
		<ul> <li>advanced systems simulation techniques: operating point, linearization, frequency domain methods, dealing with poplinearities, classical and advanced control</li> </ul>
		<ul> <li>simulation models for vertical dynamics and ride comfort</li> </ul>
		<ul> <li>suspension components: tire, damper, air spring, leaf spring, hydraulic actuator, etc.</li> </ul>
		<ul> <li>road surface and terrain models</li> </ul>
		ride comfort assessment
		active suspension: concepts, potentials, simulation
	c)	Lecture: Automotive Controller Systems
		Electrical Drives for automotive applications
		Power Electronics for AC-Drives
		Control Systems for AC-Drives (Field oriented control of a PMSM-Machine)
		Electric Vehicle modelling and Drive-Cycle simulation
		Thermal modelling of an Electrical Drive and Derating
	d)	<ul> <li>Lab: Long. Dynamics, Ride Comfort and Autom. Contr. Systems</li> <li>Modeling and simulation of linear and nonlinear flexible drivetrain</li> <li>Modeling and simulation of Toyota Prius Hybrid Drive</li> <li>Modeling and simulation of the lecture topics (PMSM-control, Drive-Cycle-Simulation, Thermal simulation/derating)</li> <li>Modeling and simulation of suspension systems</li> </ul>
5	Par	
	con	npulsory: no
	rec	ommended:
		undergraduate course in electrical engineering
		undergraduate course in computer science, programming in C or C++
		fundamentals of automotive engineering
		module ASM101 (Mathematical Methods in Engineering)
		module ASM103 (Simulation and Control 1)
6	Еха	mination Forms and Prerequisites for Awarding ECTS Points
	Wri	itten Examination 120 Min, Lab reports
7	Fur	ther Use of Module
	Ma	ster Thesis
8	Мо	dule Manager and Full-Time Lecturer
	Dro	f Dinlung Mathias Oberhauser Dinlung Georg Mallebrein Brof Dr. Polf Schulor
	rτυ	יו ביאי אישראש לשברומעשבר, שיאי אווה פרטיב אמובשרבוו, דוטו. שו. וגמו שרומובו

9	Literature Wong: Theory of Ground Vehicles. SAE Oberhauser, M.: Lecture Notes Drive-Train Modeling and Simulation Schuler, R.: Lecture Notes Ride Comfort Modeling and Simulation Mallebrein,G: Lecture Notes Electric Drives Modeling and Simulation Matlab/Simulink Student Edition and on-line Documentation
10	Last Updated 30.06.2019

## Modul ASM 3907 – Team project

1	Module Number 3907	Study Programme ASM	Semester 2	Offered in WS X SS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Points 7
2	Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
	Team Project		Project work		<b>(SWS)</b> 3	<b>(h)</b> 45	<b>(h)</b> 165	Englisch
3	Learning Outcomes Once the module has Knowledge and Und develop split con apply th underst Use, Application an Use and Transfer use met underst underst underst work w	y completed, the obtasks. In lectures and lates of project time <b>nowledge</b> project manage of systems eng engineering so	ne students can. abs on a real app e and human re ement. ineering. ftware and mea	 blication. sources. surement equip	oment.			
	<ul> <li>Scientific Innovation         <ul> <li> describe interfaces of complex systems.</li> <li> apply scientific methods to solve industrial problems.</li> <li> discuss pros and cons of new solutions in a group.</li> <li> interpret measurement data and simulation results.</li> </ul> </li> <li>Communication und Cooperation         <ul> <li> work together according to a project plan.</li> <li> consider cultural differences in working style, leadership and communication.</li> <li> cooperate within the group in order to find adequate solutions for the project task.</li> </ul> </li> <li>Scientific Self-Conception/ Professionalism         <ul> <li> work successfully in international development groups in industry.</li> </ul> </li> </ul>							
4	<ul> <li>Contents         <ul> <li>application of project management</li> <li>constitution of hierarchy (project-manager, teams members)</li> <li>constitution of project structure (time schedule, work packages</li> <li>realisation of given task</li> <li>documentation and evaluation of results</li> <li>procontation of results</li> </ul> </li> </ul>							
5	project feedback      Participation Requirements     compulsory: -     recommended: Lectures and labs of first semester							
6	<b>Examination Forms</b> Presentation in a group report	and Prerequisites	for Awarding I	ECTS Points				

## Modul ASM 3907 – Team project

7	Further Use of Module Preparation for Master thesis
8	Module Manager and Full-Time Lecturer
	Prof. Mathias Oberhauser
9	Literature
10	Last Updated
	23.04.2019

#### Modul ASM 3908 – Automotive Communications

1	Module Number 3908	Study Programme ASM	Semester 2	<b>Offered in</b> WS XSS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Points 8
2	2 Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
	<ul> <li>a) Wireless and Wired Onboard and Offboard Communication Systems</li> <li>b) Automotive Man Machine Interactions (MMI)</li> </ul>				(SWS)	(h)	(h)	
			Lecture Lecture		4	60 60	120	Englisch
3	Learning Outcomes Once the module ha	and Competences as been successfull	s y completed, th	ne students can.				
	Knowledge and Un	derstanding						
	<ul> <li> understand architecture, functionality and application of wired and wireless Onboard and Offboard communication systems.</li> <li> understand basic aspects of man machine interaction in automotive systems</li> <li>Use, Application and Generation of Knowledge</li> <li>Use and Transfer         <ul> <li> design and implement a MMI system</li> <li> setup a communication system in a vehicle</li> </ul> </li> </ul>							nmunication
	<ul> <li>Scientific Innovation</li> <li> use methods and tools to gain monitor bus systems</li> <li> independently develop approaches for new MMI concepts and assess their suitability.</li> </ul>							
	<ul> <li>Communication und Cooperation <ul> <li> communicate actively within an organization and obtain information.</li> <li> present technical contents and discuss them.</li> <li> communicate and cooperate within the group in order to find adequate solutions for the task at hand.</li> </ul> </li> </ul>							
	<ul> <li>Scientific Self-Conception/ Professionalism</li> <li> derive recommendations for decisions from a social and ethical perspective on the basis of the analyses and evaluations made.</li> </ul>							

#### Modul ASM 3908 – Automotive Communications

4	Contents Lecture a): Wireless and wired Onboard and Offboard communication systems:
	Protocol architectures of communications systems OSI/RM
	• TCP/IP
	Wireless Onboard Communication Systems
	Wired Onboard Communication Systems (vehicle busses)
	Multimedia bus (MOST)
	Lecture b): Man Machine Interaction
	• Basics
	Terms, historical view on man machine dialogue, requirements of graphical user interfaces, design requirements (software ergonomics, usability, dialog principles). On-board Pattern Recognition Systems.
	<ul> <li>machine vision systems (e.g. in traffic monitoring and automatic congestion detection, in driver assistance systems, for gesture recognition)</li> </ul>
	• speech communication: speech recognition and understanding systems, speech dialogs: speech synthesis and language
	generation (Human-Machine Interface).
	usability engineering, testing and evaluation of recognition systems
	Driver Assistance Systems
	<ul> <li>concepts for programming of driver assistance systems in automobiles: environment models, interpretation and fusion of sensor data, piloting functions, cooperative concepts.</li> </ul>
	<ul> <li>implementation of important concepts in laboratory – user-centered design</li> </ul>
	Human Factors Engineering
	human factors, such as vision, cognition
	driver attention and distraction
	usability, user-centered design     multimedal laterfaces Lab (programming everyises and procentations, simulation)
	Indutinoual interfaces Lab (programming exercises and presentations, simulation)
	Project
	selected tasks with overall semester project (group work)
	Participation Requirements
	compulsory: -
	recommended:
	Lecture a):
	Basics in communication systems and computer networks,
	Programming in C/C++/Java
	<ul> <li>Knowledge of a programming language, preferable C/C++/Java Programming in C/C++/Java</li> </ul>
6	Examination Forms and Prerequisites for Awarding ECTS Points
	Written Examination 120 min
7	Further Use of Module
	Master Thesis

#### Modul ASM 3908 – Automotive Communications

8	Module Manager and Full-Time Lecturer							
	f. A. Beck, Prof. Dr. M. Zieher, Prof. Dr. H. Melcher							
9	iterature							
	<ul> <li>Lecture a):</li> <li>Selected journal publications,</li> <li>Lecture documents,</li> <li>Gremba, Andreas (Editor): "MOST - the automotive multimedia network", Franzis Verlag, 2008, ISBN 978-3-7723-5316-1, also available as free ebook.</li> </ul>							
	<ul> <li>Karl-Friedrich Kraiss, Advanced Man-Machine Interaction . Fundamentals and Implementation (Signals and Communication Technology) Springer 2006</li> </ul>							
10	Last Updated 04.07.2019							

# Modul ASM 3909 Reliable Embedded Systems

1	Module Number 3909	Study Programme ASM	Semester 2	Offered in WS XSS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Points 8
2	Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
					(SWS)	(h)	(h)	
	a) Safety and Security		Lecture		4	60	120	Englisch
	b) Selected Topics on Real-Time Systems		Lecture		4	60		
3	Learning Outcomes Once the module ha	and Competences as been successfull	<b>s</b> y completed, th	ne students can.				
	Knowledge and Understanding							
	<ul> <li> analyze, design, and implement safety-critical distributed real-time systems</li> <li> understand safety and security issues in the development of automotive applications</li> </ul>							
	Use, Application an	d Generation of K	nowledge					
	Use and Transfer  understand the requirements for distributed real-time systems  understand and apply the concept of global time  understand the concept of fault, errors, and failures  understand event-triggered and time-triggered real-time communication  understand real-time operating systems and real-time scheduling  understand how to validate distributed real-time systems  understand the main concepts: safety, functional safety, security, information security.  understand the main concepts in security  understand security threats in the automotive domain  understand security risk management understand the main concepts in safety understand safety management according to ISO 26262							
	Scientific Innovat	ion	gain new insigh	ts in the field of	f reliable ember	Ided systems		
	Communication un	d Cooperation	Paul liew linsigh	its in the field of		aca systems		
	<ul> <li> use the to other a</li> </ul>	spects.	e, skills and cor	ipetences to ev	aluate commur	ication systems	and interpret ti	nem according
	• commu	inicate and cooper	ate within the g	roup in order to	o tind adequate	solutions for the	e task at hand.	
	<ul> <li>Scientific Self-Conception/ Professionalism</li> <li> derive recommendations for decisions from a social and ethical perspective on the basis of the analyses and evaluations made.</li> </ul>							and

#### Modul ASM 3909 Reliable Embedded Systems

#### Contents Λ Lecture a): Safety and Security Main concepts: safety, functional safety, security, information security Main concepts in security Security threats in the automotive domain, e.g. . Insecure bus systems 0 • Chip manipulation Component theft 0 Evading access controls 0 Counter measures based on cryptography . Security risk management • Safety and Security in vehicular ad hoc networks (VANETs) Main concepts in safety . Safety management according to ISO 26262 ٠ Lecture b): Selected Topics on Real-Time Systems Basic concepts for real-time systems • Distributed architectures and global time Modeling real-time systems Fault tolerance • Real-time communication . Real-time operating systems . Real-time scheduling • Validation of real-time systems • **Participation Requirements** compulsory: recommended: C/C++ programming • computer architecture basics • operating system basics object oriented modelling (UML) **Examination Forms and Prerequisites for Awarding ECTS Points** 6 Written Examination 120 min Further Use of Module 7 Master Thesis 8 Module Manager and Full-Time Lecturer Prof. Dr. D. Schoop, Prof. Dr. A. Friedrich 9 Literature • Kopetz, H.: Real-Time Systems, Kluwer 1997 • Veríssimo, P. and Rodrigues, L.: Distributed Systems for System Architects, Kluwer 2001 • Lecture material 10 Last Updated

04.07.2019

# Modul ASM 3910 – Ride and Handling

1	<b>Module Number</b> 3910	Study Programme ASM	Semester 2	Offered in WS XSS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Points 8	
2	Courses		Teaching and Forms	Learning	Conta	act Time	Self-Study Time	Language	
					(SWS)	(h)	(h)		
	a) Handling b) Transmission (	ontrol	Lecture		4	60 60	120	Englisch	
	b) Transmission control								
3	<ul> <li>Learning Outcomes and Competences         <ul> <li>Once the module has been successfully completed, the students can</li> </ul> </li> <li>Knowledge and Understanding         <ul> <li> develop an understanding of theory and methods in vehicle dynamics, with the focus on ride and handling properties</li> <li> estimate the effect of changing model parameters on ride and handling criteria.</li> </ul> </li> <li>Use, Application and Generation of Knowledge</li> </ul>								
	Use and Transfer • analyze t Scientific Innovat • apply scie	he performance ch <i>ion</i> entific tools to the	naracteristics fo development	or ride and hand	ling. Julation models.				
	Communication un work to discuss present Scientific Self-Conce justify t	d Cooperation ogether with electr new solutions for t technical content eption/ Profession the solution theore	onic and softwa suspension syst s in the field of alism tically and metl	are experts in th ems with design suspension and hodically.	e field of chassi n engineers. handling techn	s control. ology and discu	ss them.		
4	Contents								
	<ul> <li>Lecture Handling</li> <li>terminology of vehicle handling, control loop "driver-vehicle-environment", demands on vehicle handling, planar kinematics of vehicle motion, linear (bicycle) model, under- and oversteer, steady state and transient test procedures, handling characteristics under normal driving conditions, analysis and discussion of vehicle dynamics and vehicle handling including a description of the tire, nonlinear model, yaw velocity damping characteristics, effects of design parameters and the road/tire friction coefficient on handling performance</li> </ul>								
	<ul> <li>b) Lecture Suspension Modeling</li> <li>terminology in multibody dynamics, kinematics of free bodies, force and torque elements, play and friction, Newton-Euler equations, constraint functions, joints and linkages, flexible bodies, structure and functionality of multi- body codes, types of analysis, introduction into MSC.ADAMS, application in suspension modeling and simulation for ride, handling on uneven roads, and load case generation for durability</li> </ul>							uble wishbone	
5	and McPhersion Participation Requir	n suspensions in M rements	SC.ADAMS, full	vehicle simulat	ions in MSC.AD	SAMS/Car			
	compulsory								
	recommended: und	dergraduate course	e in mechanics (	especially plana	ar kinematics an	d kinetics of rig	d bodies)		
	line	ear algebra includi	ng fundamental	l matrix calculus	and eigenvalue	25 uc- sign			
	Modul 3903 Simulation and Control 1								

### Modul ASM 3910 – Ride and Handling

6	Examination Forms and Prerequisites for Awarding ECTS Points Written Examination 120 Minutes
7	Further Use of Module Master Thesis
8	Module Manager and Full-Time Lecturer Prof. Thomas Schirle
9	Literature Schindler, E.: Fahrdynamik – Grundlagen des Lenkverhaltens und ihre Anwendung für Fahrzeugregelsysteme. expert verlag, 2007 Gillespie, T.D.: Fundamentals of Vehicle Dynamics. SAE Wong: Theory of Ground Vehicles. SAE Nikravesh, P. E.: Computer-Aided Analysis of Mechanical Systems. Prentice Hall 1988 MSC: ADAMS Documentaion and Tutorials
10	Last Updated 15.06.2019

#### Modul ASM 3911 – Powertrain

1	Module Number 3911	Study Programme ASM	Semester 2	Offered in WS XSS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Points 8
2	Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
					(SWS)	(h)	(h)	
	a) Transmission S	ystems	Lecture		3	45	120	Englisch
	b) Transmission C	Control	Lecture		3	45		-
	c) Engine Control	Systems	Lecture		2	30		
		0,0000			_			
3	Learning Outcomes	and Competences as been successfull	s y completed, th	ne students can.				
	Knowledge and Un explain	derstanding the basic procedu	re of transmissi	on control	5l			
	describe     transmiss	e the design of stat ions.	te-of-the art tra	insmissions like	planetary gear s	sets, double clut	ch and continuc	ously variable
	<ul> <li>… recogni</li> </ul>	ze the significance	of transmission	n control on fue	l consumption a	nd performance	5	
	Use, Application an	d Generation of K	nowledge					
	<ul> <li>Use and Transfer</li> <li> analyze power train systems regarding speeds, torques and efficiency.</li> <li> calculate results of transient engine operation with the help of simulations.</li> <li> familiarize themselves with new ideas about engine control functions based on their basic knowledge of engine control</li> <li> analyse technical problems (e.g. caused by tolerances of components) and derive or develop solutions (adaptive engine control functions).</li> </ul>						fengine	
	<ul> <li>Scientific Innovation</li> <li> use methods and tools to gain new insights in the field of combustion engines with the help of simulation models.</li> <li> create new models and control functions in the field of combustion engines + their control.</li> <li> optimize system behaviour by calibration of parameters</li> </ul>						n models.	
	Communication un	d Cooperation						
	• work to	gether with electro	onic and softwa	are experts in th	e field of electro	onic control unit	S	
	discuss	new solutions for	powertrains wit	th design engine	eers			
	present	t technical content	s in the field of	powertrain tech	nology and disc	cuss them.	a tack at hand	
	<ul> <li>… commu</li> </ul>	inicate and cooper	ate within the g	group in order to	o ind adequate	solutions for the	e task at hand.	
	Scientific Self-Conc	eption/ Profession	alism				<b>f</b> - i	
	<ul> <li> derive r made.</li> </ul>	ecommendations	for decisions fro	om an environm	iental perspecti	e on the basis o	of simulations ar	nd calculations
	• justify solutions theoretically and methodically by presenting their simulation homework in front of the class							class

#### Modul ASM 3911 – Powertrain

4	Cont	ents				
	a)	Lecture Transmission Systems				
		<ul> <li>Calculation of vehicle performance data, Demands for vehicle transmissions Range of transmissions</li> <li>Planetary gear sets, Speed sheet, Torque calculation</li> <li>Continuously variable torque converters Mechanical variable torque converters Hydrodynamic torque converters</li> <li>Automatic transmissions Shifting components</li> <li>Power split transmission</li> <li>Hybrid transmission, parallel systems, serial systems</li> </ul>				
	b)	Lecture Transmission Control				
		<ul> <li>Electro hydraulic transmission control systems.</li> <li>Mathematical models for pressure control valves and shift process.</li> <li>Shift schedules for optimal fuel economy and best drive ability.</li> <li>Electronic control units for transmission control including interfaces and power stages.</li> <li>Driving strategy using car to car and car to infrastructure communications.</li> </ul>				
	c)	Lecture Engine Control				
		<ul> <li>Basic knowledge of the Otto combustion engine and the needed components to control the engine</li> <li>History and new trends of gasoline engines</li> <li>ECU functions for torque structure, load detection, injection time calculation and ignition timing including the control functions "idle speed control" and "Lambda control"</li> <li>Matlab / Simulink simulation model of the Otto engine and the engine control unit</li> <li>Perform simulations with parameter variation with the help of the model</li> <li>Outlook for future power train concepts like hybrid vehicles / electric vehicles</li> </ul>				
5	Parti	cipation Requirements				
	com reco	pulsory: no mmended: undergraduate course in mechanics (especially planar kinematics and kinetics) undergraduate course in hydraulics and control				
6	<b>Exan</b> Writ	nination Forms and Prerequisites for Awarding ECTS Points ten Examination 150 Minutes				
7	<b>Furtl</b> Mast	n <b>er Use of Module</b> ter Thesis				
8	<b>Mod</b> Prof.	ule Manager and Full-Time Lecturer DiplIng. Werner Klement				
9	Literature BOSCH: Automotive Handbook, Distribution SAE Klement, W.: Fahrzeuggetriebe Hanser Verlag					

#### Modul ASM 3911 – Powertrain

10 **Last Updated** 15.06.2019

## Modul ASM 3912 – Electric and Electronic Architecture

1	Module Number 3912	Study Programme ASM	Semester 2	Offered in SS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 270	<b>ECTS Points</b> 9
2	Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
					(SWS)	(h)	(h)	
	a) Electronics and Communicatio	1 n 1	Lecture	Lecture		45	135	Englisch
	b) Prototyping an	d Simulation	Lecture		1 (2)	15		
	c) Optical System	S	Lecture		4	60		
	d) Lab Optical Sys	stems	Lab		1	15		
3	<ul> <li>Learning Outcomes and Competences</li> <li>Once the module has been successfully completed, the students can describe and explain</li> <li>the coding and bus access of various automotive communication protocols</li> <li>the HW-architecture, design, prototyping and simulation of ECUs under automotive boundary conditions</li> <li>the principles of basics photometry and basics ray optic</li> <li>automotive lighting (application, interfaces, LEDs) and cameras (night vision, optical driver assistance)</li> <li>Furthermore they understand and are able to run</li> <li>experimental characterizing of optical components representing examples of automotive applications</li> </ul>							
4	Contents         a)       Lecture:         • Communication basics (e.g. coding and bus-access)         • Requirements to automotive communication (latency, protocols, communication matrix etc.)         • Protocols (e.g. CAN, CAN-FD, LIN, FlexRay, automotive Ethernet)         • Standardizations (e.g. OSEK, Autosar)         • Hardware architecture of non-permanently or permanently powered electronic control units (e.g. prototypes, placement, layout, topologies)         • Design of automotive electronics modules (e.g. reverse connection protection, analogue and digital signal acquisition, linear and switching regulators) basics to ensure EMC automotive requirements to ECUs (e.g. temperature, vibrations, power supply (e.g. jump-start, load dump))         • Electrical and behaviour simulation of electronics automotive components (e.g. by CANoe, SPICE, Matlab etc.)         • Simulation of dedicated automotive circuits photometry und ray optics, lighting and cameras         • Implementation, test and start-up of typical automotive applications         b)       Tutorial: -         c)       Lab:							
5	Participation Requirements							
	compulsory: Advanced theoretical and practical knowledge in electronics (analogue and digital) and software technologies (language C) as well as serial communication.							
	recommended: Bachelor of Engineering in Electronics, Mechatronics or similar							
6	Examination Forms and Prerequisites for Awarding ECTS Points Written examination, 150 minutes							
7	Further Use of Module none							
8	Module Manager and Full-Time Lecturer							
	Prof. Jürgen Minuth	ı, Prof. Alexander H	lornberg					
9	Literature Handouts							
10	Last Updated 18 <sup>th</sup> of June 2019							

# Modul ASM 3913 – Packaging and Integration

1	Module Number 3913	Study Programme ASM	Semester 2	Offered in SS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Points 7
2	Courses Teaching and Learni		Learning Forms	Contact Time		Self-Study Time	Language	
					(SWS)	(h)	(h)	
	a) Packaging and	Wire Harness	Lecture		2	30	105	Englisch
	b) Automotive EN	ЛС	Lecture		1	15		-
	c) Electronics and	1	Lecture	lecture		30		
	Communicatio	n 2			_			
	d) Lab Car Electro	onics	Lab		2	30		
3	<ul> <li>Learning Outcomes and Competences</li> <li>Once the module has been successfully completed, the students can describe and explain</li> <li>ECU topologies, the electro-magnetic behaviour of cables, signal shapes in the time domain</li> <li>Sources of interferences, measurement procedures, design rules.</li> <li>Protocol circuits, physical layer components, electrical requirements to ECUs, distributed communication, signal levels, modelling of ECU's behaviour.</li> <li>Furthermore they understand and are able to run</li> <li>the design, test and start-up of electronic systems for automotive applications.</li> </ul>							
4	Contents         a)       Lecture:            Protocol circuits and transceiver (e.g. CAN, CAN-FD, LIN, FlexRay, automotive Ethernet)             ECU technologies             electro-magnetic behaviour of cables             Standardized SW-modules (e.g. network management, communication and operating system)             Aspects of EMC when using e.g. switched inductive loads, valves, stepper motors, busses             Aspects of EMC sceneries e.g. ground bounce (statically and dynamically), common mode and differential mode, X-talk, radiation and irradiation, Faraday cage approaches to handle EMC e.g. common mode coils, ferrites, capacitors, layout, ground connections, arrangement of the wiring, shielding, specifications and interfaces, cables and wiring harness, cable channel, splices, available, lead through, cut point (connectors)             Technologies of ECUs e.g. standard design with printed circuit boards and surface mounted devices up to thick film integration modules with bond-out chips gateways             Levels of abstraction e.g. applications, functions, tasks, signals, PDUs; ECUs, messages simulations e.g. rest-bus, transmissions lines, electromagnetic fields          b)       Tutorial: -         c)       Lab:         The content depends on the specified requirements for the module 3907 named team project; examples are introductions into CANoe, LT-Spice or Altium designer							
5	Participation Requirements							
	compulsory: Advanced theoretical and practical knowledge in electronics (analogue and digital) and software technologies (language C) as well as serial communication.						chnologies	
	recommended: Ba	recommended: Bachelor of Engineering in Electronics, Mechatronics or similar						
6	Examination Forms	and Prerequisites	for Awarding E	CTS Points				
	written examination, 150 minutes							
/	none	luie						
8	Module Manager a	nd Full-Time Lectu	rer					
	Prof. Jürgen Minuth	, Prof. Gerd Wittle	r					
9	Literature							
	Handouts							
10	Last Updated							
	18 <sup>th</sup> of June 2019							

#### Modul ASM 3914– Softskills

1	<b>Module Number</b> 3914	Study Programme ASM	Semester 1	Offered in WS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Points 7
2	Courses		Teaching and Forms	Learning	Conta	act Time	Self-Study Time	Language
					(SWS)	(h)	(h)	
	a) Global Enginee	ring	Lecture		2	45	105	Englisch
	b) Project Manage	ement	Lecture		2	45		
	c) International N	egotiations	Lecture		2	45		
3	Learning Outcomes and Competences Once the module has been successfully completed, the students can Knowledge and Understanding							
	<ul> <li> underst</li> <li> underst</li> <li> develop</li> <li> apply th</li> <li> underst</li> <li> know at</li> <li> know cu</li> <li> improve</li> <li> underst</li> </ul>	<ul> <li> understand sales &amp; marketing aspects of global engineering projects.</li> <li> understand different approaches towards global engineering projects (waterfall, agile, hybrid project management).</li> <li> develop a project plan, split complex tasks into subtasks.</li> <li> apply the knowledge from lectures and labs on a real application.</li> <li> understand the limitations of project time and human resources.</li> <li> know about Intellectual properties and patent topics in engineering</li> <li> know cultural differences.</li> <li> improve language and mimic as a tool of successful interaction</li> <li> understand mechanisms of multilateral business and trade formals</li> </ul>						
	Use, Application an	d Generation of K	nowledge					
	Use and Transfer							
	<ul> <li>Communication und Cooperation <ul> <li> work together according to a project plan</li> <li> take into account cultural differences in working style, leadership and communication.</li> <li> cooperate within diverse international groups in order to find adequate solutions for the project task.</li> <li> lead project teams</li> <li> achieve more satisfying business output of international negotiations</li> <li> use the right negotiation options according to the specific (cultural) counterparts</li> <li> handle difficult situations and settle conflicts peacefully</li> </ul> </li> </ul>							
	Scientific Self-Conce	eption/ Profession ccessfully in intern	alism ational develop	oment groups in	industry.			

#### Modul ASM 3914– Softskills

4	Contents
	a) and b) (Global Engineering & Project Management)
	Sales & Marketing Aspects of Engineering Projects
	- Project lifecycle and analysis
	- Branding
	- Key Account Management
	- Customer Management
	- Bid management
	Intellectual Property and Patents
	- Basics of Intellectual Property Rights (IPR)
	- Global Corporate Patent Strategy and Management
	- Company examples
	Classical Project Management
	- Project Management Processes
	<ul> <li>Functions and responsibilities of a project manager</li> </ul>
	- Scope, Time, Quality & Risk Management
	- Communications, HR & Integration Management
	<ul> <li>Documentation, reporting, presentation, decision making</li> </ul>
	Agile and Hybrid Project Management
	- Overview of different agile methods
	- Scrum
	<ul> <li>Integration of classical and agile methods</li> </ul>
	Critical Chain Project Management (CCPM)
	- Gamification with theoretical inputs
	- application of project management to a case study
	Supporting IT structures
	- IT Network and Infrastructure
	- IT Organisation
	- IT Security
	- Managing Product Data
	- From Engineering to Production
	c) International Negotiations
	Background toaching of cultural difforences
	<ul> <li>Decograding of cultural differences</li> <li>Interactive / international role plays</li> </ul>
	<ul> <li>Exchanging of experiences of husiness and other cross-cultural transactions and achievements / failures</li> </ul>
	<ul> <li>Discourse and examples aimed at improving individual skills / arguments</li> </ul>
	<ul> <li>Win-win situations – learning different methods of negotiations</li> </ul>
	Participation Requirements
	• compulsory: -
	recommended: Negotiation English
	Some basic business experience
	Basic multicultural skills
6	Examination Forms and Prerequisites for Awarding FCTS Points
	a) and b) (Global Engineering & Project Management)
	• 90 min written evam
	Presentation in a group , 20 minutes
	c) International Negotiations
	60 min written exam (based on attending class and role plays)
7	Further Use of Module
	Module Team Project, Preparation for Master thesis, Preparation for negotiations in job sitatuions
8	Module Manager and Full-Time Lecturer
	Prof. Dr. Siegfried Zürn
	- plus external experts and lecturers

#### Modul ASM 3914– Softskills

9	Literature	
	•	Script and case studies will be provided in electronic format
	•	PMBOK Guide 8 <sup>th</sup> edition, PMI Institute
	•	Larson, E.W.; C.F. Gray (2016): Project Management – The Managerial Process, McGraw-Hill
	•	Mühlen, Alexander (2010): International negotiations, Münster Verlag, 2010
10	Last Updat	ed
	2019-06-1	3

## Modul ASM 3915 – Master Thesis

1	Module Number 3915	Study Programme ASM	Semester 3	Offered in X WS SS	<b>Duration</b> 1 Semester	Module Type compulsory	Workload (h) 690	ECTS Points 23
2	Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
	Master Thesis Master Thesis Presentation and		Thesis Presentation		(SWS) 2 1	(h) 30 15	<b>(h)</b> 600 45	Englisch
3	Learning Outcomes and Competences         Once the module has been successfully completed, the students can         Knowledge and Understanding         • handle and solve a problem with scientific methods on their own         Use, Application and Generation of Knowledge         Use and Transfer         • do scientific literature research .         • write a scientific report.         • organize themselves.         ····         ····         Scientific Innovation         • understand the theories and their limitations in there engineering discipline.         ····         ····         Communication und Cooperation         • write together with technical staff in industrial labs.         • work together with their own department and other departments and suppliers.         Scientific Self-Conception/ Professionalism         •work in R&D departments in industry         • join a PID program							
4	Contents  • constitution of • realisation of • documentation • presentation	of project structure given task with sci on and evaluation o and defense of res	(time schedule entific methods of results ults	e, work packages and within a giv	s) ven timeframe			
5	Participation Requirements compulsory: - recommended: Lectures and labs of first and second semester, team project							
6	Examination Forms Presentation and or Thesis report	and Prerequisites	for Awarding E	CTS Points				
7	Further Use of Mod Preparation for Mas	<b>lule</b> ster thesis						

#### Modul ASM 3915 – Master Thesis

8	Module Manager and Full-Time Lecturer
	Prof. Mathias Oberhauser
9	Literature
10	Last Updated 23.04.2019